## FLUKA Combinatorial Geometry

## Beginners FLUKA Course

## Introduction

Principle of Combinatorial Geometry: Basic convex shapes (bodies) like cylinders, spheres, parallelepipeds, etc. are combined to more complex shapes called regions. This combination is done by the boolean operations union, intersection and subtraction.

The Combinatorial Geometry used by FLUKA is loosely based on the package developed at ORNL for the neutron and gamma-ray transport program Morse (M.B. Emmett ORNL-4972 1975) which was based on the original combinatorial geometry by MAGI (Mathematical Applications Group, Inc., W. Guber et al, MAGI-6701 1967).

## Input

- The input format for the geometry is different from that adopted elsewhere in FLUKA, i.e. the number and length of the input fields is different.
- The recommended format is called free format. For backward compatibility there are also other formats. Free format is not the default one!
- One advantage of free format is that alignment of the input parameters is not necessary. Bodies and regions are identified by names.
- In fixed format alignment is mandatory. Bodies and regions are identified by numbers and not by names which makes creation and updating of the geometry difficult.


## Basic Concepts

Four concepts are fundamental in the FLUKA CG:

- Bodies - basic convex objects + infinite planes \& infinite cylinders
- Zones - sub-region defined only with intersection and subtraction of bodies (used internally)
- Regions - are defined as boolean operations of bodies (union of zones)
- Lattices - duplication of existing objects (translated \& rotated)

In the original description bodies were convex solid bodies (finite portions of space completely delimited by surfaces of first or second degree, i.e. planes or quadrics). In FLUKA, the definition has been extended to include infinite cylinders (circular and elliptical) and planes (half-spaces).

Use of such "infinite bodies" is encouraged since it makes input less error-prone. They also provide a more accurate and faster tracking.

## Bodies

- Each body divides the space into two regions inside and outside. The outside region is pointed to by the normal on the surface.
- 3-character code of available bodies:
- RPP: Rectangular parallelepiped
- SPH: Sphere
- XYP, XZP, YZP: Infinite half space delimited by a coordinate plane
- PLA: Generic infinite half-space
- XCC, YCC, ZCC: Infinite circular cylinder, parallel to coordinate axis
- XEC, YEC, ZEC: Infinite elliptical cylinder, parallel to coordinate axis
- RCC: Right circular cylinder
- REC: Right elliptical cylinder
- TRC: Truncated right angle cone
- ELL: Ellipsoid of revolution
- Other bodies ARB, RAW, WED, BOX
- don't use them, they cause sometimes rounding problems


## The Black Hole

To avoid infinite tracking the particles must stopped somewhere. This has to be insured by the user by defining a region surrounding the geometry and assigning the material BLCKHOLE to it.

All particles that enter the blackhole are absorbed (they disappear). Further blackhole regions can be defined by the user if necessary.

The blackhole is the outermost boundary of the geometry. Inside the blackhole region:

## Each point of space must belong to one and only one region!

## Combinatorial Geometry Input

CG input must respect the following sequential order:
GEOBEGIN card
VOXELS card (optional, see Voxel lecture) Geometry title (and reading format options) Body data
END card
Region data
END card
LATTICE cards (optional, see Lattice lecture)
Region volumes (optionally requested by a flag in the Geometry title, used together with SCORE)
GEOEND card

Cards having a * in column 1 are treated as comments.

## Free format

Free format has been introduced recently and is recommended with respect to the other formats, which will be kept however for reasons of back compatibility. Its main advantages, in addition to the freedom from strict alignment rules, are the possibility to modify the input sequence without affecting the region description (for instance, by inserting a new body) and the availability of parentheses to perform complex boolean operations in the description of regions.

Free format input is used for both body and region if requested by COMBNAME in the GEOBEGIN card, or by a GLOBAL command at the beginning of the input file.

## GEOBEGIN card

The meanings of the WHAT and SDUM parameters are:
WHAT(1) flag for switching off geometry error messages: don't touch!!
Default $=0.0$ (all geometry error messages are printed)
WHAT(2) used to set the accuracy parameter - use with care!
WHAT(3) = logical unit for the geometry input.
If $>0.0$ and different from 5 , the name of the corresponding file must be input on the next card. Otherwise, the geometry input follows.
WHAT(4) = logical unit for the geometry output. If $>0.0$ and different from 11, the name of the corresponding file must be input on the next card. Otherwise, geometry output is printed on the standard output.
WHAT(5) Parenthesis optimization level (see FLUKA manual)
WHAT(6) not used
SDUM = COMBNAME or COMBINAT
COMBNAME selects free format, COMBINAT fixed format Default: COMBINAT (!)
Can be overwritten by WHAT(5) of a possible GLOBAL card

## The geometry title card

This card has no keyword, it is the line that follows the GEOBEGIN card (unless voxels are used).
Three variables are input in the CG Title card: IVOPT, IDBG, TITLE. The format is (2I5, 10X, A60).
The first integer value (IVOPT = Input Volumes OPTion) indicates how to normalize the quantities scored in regions by the option SCORE IVOPT $=0 \rightarrow$ no region volumes will be input before GEOEND
IVOPT $=3 \rightarrow$ region volumes will be input before GEOEND. As many volume values must be input as there are geometry regions, in this format: (7E10.5).

IDBG is a flag used to request different kinds of geometry fixed format input.
IDBG $=0$ activates free format
IDBG $=-10$ or -100 activates fixed and high accuracy format

## Bodies

The input for each body consists of

- the 3-letter code indicating the body type
- a unique "body name" (8 character maximum, alphanumeric identifier, case sensitive)
- a set of geometrical quantities defining the body (their number depends on the body type as explained below).
A maximum of 132 characters per line are accepted, use extra lines if required.

The different items, separated by one or more blanks, or by one of the separators , / ; : can extend over as many lines as needed.

## All numbers are in cm!

## Rectangular Parallelepiped: RPP

An RPP has its edges parallel to the coordinate axes. It is defined by 6 numbers in the following order:

$$
\mathbf{X}_{\min }, X_{\max }, \mathbf{Y}_{\min }, \mathbf{Y}_{\max }, \mathbf{Z}_{\min }, \mathbf{Z}_{\text {max }}
$$

(minimum and maximum coordinates which bound the parallelepiped).x


## Rectangular Parallelepiped: RPP

Free format
RPP Sm1Brick -20.0 +20.0 -50.0 +50.0 -38.5 +38.5
An RPP definition extends over one single card in default fixed format, or over two cards in high-accuracy body fixed format 4 kinds of infinite halfspaces.

Example in fixed format (the comment lines shown are allowed input lines):


* (a parallelepiped centered on the origin)

High-accuracy fixed format


## Sphere and circular cylinder

## Sphere: SPH

A SPH is defined by 4 numbers: $\mathbf{V x}, \mathbf{V y ,} \mathbf{V z}$ (coordinates of the centre), $\mathbf{R}$ (radius)

## Right circular cylinder: RCC

An RCC can have any orientation in space. It is limited by a cylindrical surface and by two plane faces $\perp$ to its axis. Each RCC is defined by $\mathbf{7}$ numbers:
$\mathbf{V x}, \mathbf{V y}, \mathbf{V z}$ (centre of one face); $\mathbf{H x}, \mathbf{H y}, \mathbf{H z}$ (vector corresponding to the cylinder height, pointing to the other face); $\mathbf{R}$ (cylinder radius).


## Infinite half-space parallel to coordinate axis

There are 4 kinds of infinite half-spaces.
Three are delimited by planes perpendicular to the coordinate axes:

1. Delimited by a plane $\perp$ to the $\mathbf{x}$-axis. Code: YZP
2. Delimited by a plane $\perp$ to the $\mathbf{y}$-axis. Code: XZP
3. Delimited by a plane $\perp$ to the $\mathbf{z}$-axis. Code: XYP All defined by a single number: $\mathbf{V x}$ (resp. $\mathbf{V y}$, or $\mathbf{V z}$ ), the coordinate of the plane on the corresponding perpendicular axis.

The half-space "inside the body" is the position of points for which:
$\mathbf{x}<\mathbf{V x}$ (resp. $\mathbf{y}<\mathbf{V} \mathbf{y}$, or $\mathbf{z}<\mathbf{V z}$ )


## Arbitrarly orientated infinite half-space: PLA

A PLA defines the infinite half space delimited by a generic plane. A PLA is defined by 6 numbers:
$\mathbf{H x}, \mathbf{H y , H z}$ (vector of arbitrary length $\perp$ to the plane);
$\mathbf{V x}, \mathbf{V y ,} \mathbf{V z}$ (any point lying on the plane). The half-space "inside the body" is that from which the vector is pointing (i.e. the vector points "outside").

## Infinite cylinders

Infinite Circular Cylinder || to coordinate axis: XCC, YCC, ZCC Each XCC ( YCC, ZCC) is defined by 3 numbers: Ay, Az for XCC ( $\mathbf{A z}, \mathbf{A x}$ for YCC, $\mathbf{A x}, \mathbf{A y}$ for ZCC) (coordinates of the cylinder axis), $\mathbf{R}$ (cylinder radius)

Infinite Elliptical Cylinder || to coordinate axis: XEC, YEC, ZEC Each XEC ( YEC, ZEC) is defined by 4 numbers: Ay, Az for XEC ( $\mathbf{A z}, \mathbf{A x}$ for YEC, $\mathbf{A x}, \mathbf{A y}$ for ZEC) (coordinates of the cylinder axis); $\mathbf{L y}$, Lz for XEC (Lz, Lx for YEC, Lx, Ly for ZEC) (semi-axes of the ellipse)

## Regions

## Concept

Regions are defined as combinations of bodies obtained by boolean operations:

|  | Union | Subtraction | Intersection |
| :---: | :---: | :---: | :---: |
| Free Format | I | - | + |
| Fixed format | OR | - | + |
| Mathematically | $\cup$ | - | $\cap$ |

Regions are not necessarily simply connected (they can be made as the union of two or more non contiguous or partially overlapping zones) but must be of homogeneous material composition.

## Regions

Input for each region starts on a new line and extends on as many continuation lines as are needed. It is of the form:

## REGNAME NAZ boolean-zone-expression

> or

## REGNAME NAZ boolean-zone-expression / boolean-

 zone-expression / ...- REGNAME is the region "name" (an arbitrary unique alphanumeric character string chosen by the user). The region name must begin by an alphabetical character and must not be longer than 8 characters.
- $N A Z$ is a rough guess for the number of regions which can be entered leaving the current region, normally 5
- "boolean-zone-expression" is a sequence of one or more body names preceded by the operators + (intersection) or - (complement or substraction). A zone expression can be contained inside one set of left and right parentheses. Several zone expressions can be combined by the union operator I.


## Regions

- | operators are used to join zones defined all bodies between them, each body being preceded by its $\boldsymbol{+}$ or - sign.
- In evaluating the expressions, the highest operator precedence is given to parentheses, followed by $\boldsymbol{+}$, and the I operator.
- If one line is not sufficient, any number of continuation lines can be added.
- Blanks are ignored.


## Meaning of + and - operators

If a body number appears in a zone description preceded by a $\boldsymbol{+}$ operator, it means that the zone being described is wholly contained inside the body.

If a body number appears in a zone description preceded by a operator, it means that the zone being described is wholly outside the body.

Zones must be finite: obviously, in the description of each zone and hence of each region the symbol + must appear at least once.

## Illustration of the $\boldsymbol{+}$ and $\boldsymbol{-}$ operators



## Meaning of the +- operators

Target 4 +Outer +CutPlane

* (the above region is the part of space common to bodies Outer and
* CutPlane)

Regex 7 +Red -Blue -Green +Yellow

* (the above region is the part of space common to body Red and Yellow,
* excluding however that which is inside body Blue and that which is
* inside Green)

Air 5 +Room

* (the latter region coincides entirely with body Room)


## Meaning of the | (OR) operator

The | (or OR) operator is used as a boolean union operator in order to combine zones (subregions partially overlapping or not). Zones are formed as intersections or differences as explained above, and then the region is formed by a union of these zones.
Examples:


| Ground 51 +Body9 \| +Body15 | +Body1 | +Body8 -Body2 | +Body8 -Body3 |  |
| :---: | :---: |
| * | <- 1st -><- 2nd -><- 3rd -><---- 4th ----><---- 5th ----> |
|  | \| +Body8 +Body18 | +Body12 -Body10 -Body11 -Body13 -Body14 |
| * | <----- 6th -----><------- 7th and last subregion --------> |
|  | (continuation line) |

## Parenthesis

Parentheses are grouping together combinations of bodies.
Parentheses can be used in free format only.
Examples:

```
*...+....1....+....2....+....3....+....4....+....5....+....6....+.....7...
* Subtract from body2 regions regR03, regR04, regR05
regV02 5 +body2 - (+body4 -body3)
    - (+body6 -body5 |+body8 -body7) - body9 -body10
regR03 5 +body4 -body3
regR04 5 +body6 -body5 |+body8 -body7
regR05 5 +body9 | +body10
```

Nested parentheses are supported, however:
parentheses should be used with care since their expansion can generate a quickly diverging amount of terms. A partial optimization is performed on planes (aligned with the axes) and bounding boxes only

## Important Notes

- Whenever it is possible, the following bodies should be preferred:

$$
\begin{array}{|l|}
\hline \text { PLA, RPP, SPH, XCC, XEC, XYP } \\
\text { XZP, YCC, YEC, YZP, ZCC, ZEC }
\end{array}
$$

These make tracking faster, since for them extra coding ensures that unnecessary boundary intersection calculations are avoided when the length of the next step is smaller than the distance to any boundary of the current region.

- Always use as many digits as possible in the definition of the body parameters, particularly for body heights (RCC, REC), and for direction cosines of bodies with slant surfaces. The free format or the high-accuracy fixed format should always be used in these cases.
- Avoid as much as possible using two bodies which share independently the same surface (e.g. two RPP's with a common face). Rather make one or both bigger and cut both with a common plane.


## Precision Errors

Modeling assumptions


Especially when floating point operations are involved.

- Use cutting surfaces B instead.

- Or force partial overlap of objects



## Precision Errors

FLUKA uses double precision arithmetic:

- Double precision significant digits 16
- Due to rounding errors: $\sim 14$ significant digits
- Precision is relative to the position.
- Avoid objects like:
- BOX: arbitrary oriented in space. It is difficult to ensure perpendicularity of the surfaces
- ARB, WED: use surfaces instead
- If and only if there is no other solution, one can relax the geometry precision with the WHAT(2) on the GEOBEGIN card. USE WITH CAUTION!


# Geometry Errors and Debugging 

## Geometry Errors

- During execution the code always needs to know the region where a particle is located at every step.
- The program will stop only if a particle's position doesn't not belong to any region.
It will issue an error message on the .err file with the particle position.
- IMPORTANT! It will not stop if a particle's position belongs to more than one region. It will accept the first region it finds but results will be meaningless!!



## Some hints

- Never start a particle from a surface. You could get a geometry error even if the geometry is correct because FLUKA cannot determine the region.
- FLUKA tries to correct this by moving the particle a bit.
- However if it happens too often the run will stop.
- To avoid this the starting point of the beam particle must be slightly moved
- Never eject a particle along a surface (for the same reason)


## Geometry Debugging

Possible types of errors

- "Point" belonging to more than one region
- The program will not stop during execution, nor a error message will appear!
- "Point" not belonging to any region
- The program will stop with an error message when a particle will enter to this region
- Universe not enclosed by a black body region (Geometry = Universe + Black hole)
- Precision errors
- Lattice replica $\leftarrow \rightarrow$ basic cell mismatch (see lattice lecture) Debugging Tools
- GEOEND card with the DEBUG option
- Error messages during simulation
- PLOTGEOM card (see manual, used automatically by Flair)


## Debugging

GEOEND card activates the geometry debugger. Detects both undefined or multiple defined points in a selected $X, Y, Z$ mesh

- Two cards are needed

First card

$$
\begin{aligned}
& \text { WHAT(1) }=X_{\text {max }} \quad \text { WHAT(2) }=Y_{\text {max }} \quad \text { WHAT(3) }=Z_{\text {max }} \\
& \text { WHAT(4) }=X_{\text {min }} \quad \text { WHAT(5) }=Y_{\text {min }} \\
& \text { WHAT(6) }=\mathrm{Z}_{\text {min }} \\
& \text { WHAT(1) }=\mathrm{Nx} \quad \text { WHAT(2) }=\mathrm{Ny} \\
& \text { WHAT(3)=Nz }
\end{aligned}
$$

- Second Card


## GEOEND Xmax Ymax Zmax Xmin Ymin Zmin DEBUG GEOEND Nx Ny Nz <br> \&

WARNING!
The program stops if too many errors are found.
A message will be issued on the output unit.

## Debugging

- If no error is found, no .err file will be created.
- REMINDER: If the debugger doesn't find any error it doesn't mean that the geometry is error free!
- One has to experiment, changing the GEOEND settings especially for the critical/complicated regions.
- Errors will be listed in the .err file in the form:
**** Lookdb: Geometry error found ****
**** The point: -637.623762-244.554455-96.039604 ****
- Point is contained in more than one region
**** is contained in more than 1 region ${ }^{* * * *}$
**** (regions: 6 7) ${ }^{* * * *}$
- Not contained in any region
**** is not contained in any region


## Auxilliary program: Simple Geo



## Auxiliary program: SimpleGeo

- SimpleGeo is an interactive solid modeler which allows for flexible and easy creation of the models via drag \& drop, as well as on-the-fly inspection
- Imports existing geometries for viewing
- Creating new geometries from scratch
- Export to various formats (FLUKA, MCNP, MCNPX)
- Download, Tutorials, etc.: http://theis.web.cern.ch/theis/simplegeo
- Operating system: Windows only



## The geometry title card: IDBG

The second integer value IDBG can be used to modify the format with which body and region data are read:

## IDBG

0 or 10 default fixed format for both bodies and regions
-10 high-accuracy fixed format for bodies; default fixed region
-100 high-accuracy fixed format for bodies; region fixed format allowing more than 10000 regions
100 default fixed format for bodies; region fixed format allowing more than 10000 regions
Any other value should be avoided.

The value of IDBG is irrelevant if free format has been requested (see the GLOBAL and GEOBEGIN commands)

## The fixed geometry input format: regions

Each body is referred to by its sequential number in the body description table.

Input for each region extends on one or more cards, in a format which depends on the value of IDBG on the Geometry Title card.
If $\operatorname{IDBG}=0,10$ or -10 , region input format is

$$
(2 X, A 3, I 5,9(A 2, I 5))
$$

if IDBG $=100$ or -100 , region input format is
( $2 \mathrm{X}, \mathrm{A} 3, \mathrm{I} 5,7(\mathrm{~A} 2, \mathrm{I} 7)$ )

## The fixed geometry input format: regions

The 3 characters in columns 3-5 are:

- on the first card of a given region, an arbitrary non-blank string chosen by the user (it can be used, together with optional comment cards, to help identifying the region or the region material).

Note: that regions are identified in FLUKA by an integer number corresponding to the order of their input definition. Therefore it can be useful (but not mandatory) to have that number appearing in the string.

For instance, if the 5th region is air, it could be labeled AI5.

On all continuation cards, columns 3-5 must be blank.

## Parentheses Expansion

- Parentheses expansion is almost like converting from: product of sums
to: sum of products
- Product operators are: +/-, Sum operator: |
- The final result will be an expression in the normal form. Unions of all possible combinations of the bodies in the expression!
- Initially the code removes all repeated terms:

$$
\begin{array}{ll}
A+A & =A \\
A-A & =\varnothing \\
\exp A \mid \operatorname{expA} & =\exp A
\end{array}
$$

Use parentheses with care!!!
It can easily create an expansion with thousands of terms!

## Parentheses Expansion



## Parentheses Expansion

BLACK Region (36/108)
OR +Bottom1 +Bottom2 +EXTVOID
OR +Bottom1 +EXTVOID + Front2
OR +Bottom1 +EXTVOID + Right2
OR +Bottom1 +EXTVOID -Back2
OR +Bottom1 +EXTVOID -Left2
OR +Bottom1 +EXTVOID -Top2
OR +Bottom2 +EXTVOID +Front1
OR +Bottom2 +EXTVOID + Right1
OR +Bottom2 +EXTVOID -Back1
OR +Bottom2 +EXTVOID -Left1
OR +Bottom2 +EXTVOID -Top1
OR +EXTVOID +Front1 +Front2
OR +EXTVOID +Front1 + Right2
OR +EXTVOID +Front1 -Back2
OR +EXTVOID +Front1 -Left2
OR + EXTVOID +Front1 -Top2
OR +EXTVOID +Front2 + Right1
OR +EXTVOID +Front2 -Back1
OR +EXTVOID +Front2 -Left1
OR +EXTVOID +Front2 -Top1
OR +EXTVOID + Right1 + Right2
OR +EXTVOID + Right1 -Back2
OR +EXTVOID +Right1 -Left2
OR +EXTVOID + Right1 -Top2
OR +EXTVOID + Right2 -Back1
OR +EXTVOID + Right2 -Left1

OR +EXTVOID + Right2 -Top1
OR +EXTVOID -Back1 -Back2
OR +EXTVOID -Back1 -Left2
OR +EXTVOID -Back1 -Top2
OR +EXTVOID -Back2 -Left1
OR +EXTVOID -Back2 -Top1
OR +EXTVOID -Left1 -Left2
OR +EXTVOID -Left1 -Top2
OR +EXTVOID -Left2 -Top1
OR +EXTVOID -Top1 -Top2

## CUBE1 Region (1/6)

+Back1 +Left1 +Top1 -Bottom1 -Front1 -Right1

## CUBE2 Region (6/42)

OR +Back2 +Bottom1 +Left2 +Top2 -Bottom2 -Front2 -Right2
OR +Back2 +Front1 +Left2 +Top2 -Bottom2 -Front2 -Right2
OR +Back2 +Left2 + Right1 +Top2 -Bottom2 -Front2 -Right2
OR +Back2 +Left2 +Top2 -Back1 -Bottom2 -Front2 -Right2
OR +Back2 +Left2 +Top2 -Bottom2 -Front2 -Left1 -Right2
OR +Back2 +Left2 +Top2 -Bottom2 -Front2 -Right2 -Top1

## Region Optimization

Geometrical optimization can drastically reduce the number of subzones.
Currently work is going on for 2 types of optimization to be implemented in FLUKA

1. Elimination of same type of planes (XYP, XZP, YZP) inside a subzone (product).
2. Optimization of sub-zones based on the bounding boxes of the bodies.

- Infinite objects have an infinite bounding box on some of the dimensions ie. XYP, ZCC etc.
- PLAnes do not have a bounding box
- For each sub-zone after the expansion, if the intersection of the bounding boxes is impossible the sub-zone is discarded


## Expansion Optimization

```
BLACK Region (30/90)
OR +Bottom1 +EXTVOID
OR +Bottom1 +EXTVOID +Front2
OR +Bottom1 +EXTVOID +Right2
OR +Bottom1 +EXTVOID -Back2
OR +Bottom1 +EXTVOID -Left2
OR +Bottom2 +EXTVOID +Front1
OR +Bottom2 +EXTVOID +Right1
OR +Bottom2 +EXTVOID -Back1
OR +Bottom2 +EXTVOID -Left1
OR +EXTVOID +Front2
OR +EXTVOID +Front1 +Right2
OR +EXTVOID +Front1 -Left2
OR +EXTVOID +Front1 -Top2
OR +EXTVOID +Front2 +Right1
OR +EXTVOID +Front2 -Left1
OR +EXTVOID +Front2 -Top1
OR +EXTVOID +Right1
OR +EXTVOID +Right1 -Back2
OR +EXTVOID +Right1 -Top2
OR +EXTVOID +Right2 -Back1
OR +EXTVOID +Right2 -Top1
OR +EXTVOID -Back1
OR +EXTVOID -Back1 -Left2
OR +EXTVOID -Back1 -Top2
OR +EXTVOID -Back2 -Left1
```

```
OR +EXTVOID -Back2 -Top1
```

OR +EXTVOID -Back2 -Top1
OR +EXTVOID -Left2
OR +EXTVOID -Left2
OR +EXTVOID -Left1 -Top2
OR +EXTVOID -Left1 -Top2
OR +EXTVOID -Left2 -Top1
OR +EXTVOID -Left2 -Top1
OR +EXTVOID -Top2

```
OR +EXTVOID -Top2
```


## CUBE1 Region (1)

```
+Back1 +Left1 +Top1 -Bottom1 -Front1 -Right1
```


## CUBE2 Region (3/18)

```
OR +Front1 +Left2 +Top2 -Bottom2 -Front2 -Right2 OR +Back2 +Left2 +Top2 -Bottom2 -Front2 -Left1
OR +Back2 +Left2 +Top2 -Front2 -Right2 -Top1
```


# The optimization process can correct only for some of the "obvious" things 

